

## Introduction + Theory

## Background:

- Many MR measures are indirectly inferred from multiple measurements. (e.g. the tag and the control image in arterial spin labelling or multi-TE images for relaxometry).
- Reconstruction and decoding of the signal of interest are often treated separately.
- Instead, treating them jointly opens up new degrees of freedom.
- Modern MRI is often undersampled and reconstructed with compressed sensing.

## Theory:

- The acquisition operator,  $E$ , and the point-spread-function (PSF =  $E^T E$ ) determines the spreading of artefacts and is generally shift invariant.
- Incoherence of  $E$  is essential for compressed sensing: to work.
- When reconstruction and decoding of the signal are treated separately, we can only influence the incoherence of  $E$  through choice of trajectory.
- When considering reconstruction and decoding jointly, a more optimal combination of trajectory and encoding can be developed.

## In this work:

- We used an example framework to investigate sampling and encoding interactions: golden angle radially sampled vessel-encoded arterial spin labelling (VE-ASL)<sup>2</sup>.
- We developed a tool called the multidimensional point-spread-function (m-PSF) to explore these types of interactions.
- The m-PSF was generated by transforming ( $E^T E$ ) a delta function centred in each component and measuring its effect on every other component.

## Methods

## Simulated encoding-trajectory interactions:

- Same trajectory for each encoding + 4x4 Hadamard encoding of 3 vessels and static tissue (Fig 1a – no rotation)
- Different trajectory for each encoding (45° rotated) + 4x4 Hadamard encoding (Fig 1a)
- Different trajectory for every other encoding with half the number of spokes per encoding compared with method 1. and 2 + paired 8x4 Hadamard encoding (Fig 1b)

## Reconstruction strategies:

- Reconstruct first – then decode (Fig 2a)
- Decode first – then reconstruct (Fig 2b)
- Joint reconstruction + decoding (Fig 2c)

- Compressed sensing optimisation using the Fast Iterative Soft Thresholding Algorithm (FISTA<sup>3</sup>) was used minimising sparsity of the image in its native space:

$$\text{cost} = \frac{1}{2} \|Ex - d\|_2^2 + \lambda \|x\|_1$$

- $\lambda = 5$  for all methods

## Data + simulation setup:

- 10 augmentations of a digital VE-ASL phantom were used and 10 instances of complex gaussian noise were added to each before reconstruction.
- The background component had approximately 10 times higher signal than the vessel components. Total background suppression was also tested (component 4 set to zero).
- Images were reconstructed from a total of 16 or 64 spokes spread across the encodings.

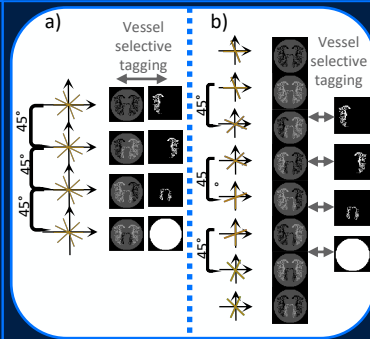


Fig 1 – Four components (3 vessels + 1 background) are encoded into four (a) or eight (b) encoded images that are acquired with a radial trajectory that is rotated for some of the encodings.

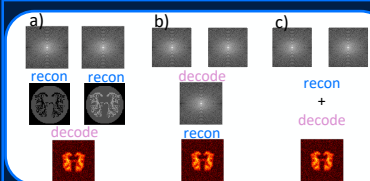


Fig 2 – To find a property of interest you can either reconstruct then decode (a), decode and then reconstruct (if same sampling points) (b), or do a joint reconstruction and decoding.

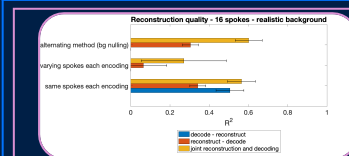


Fig 4 – Varying spokes each encoding is bad because the static tissue swamps the vessel components. The alternating spokes approach removes the background but samples more locations in k-space than using the same spokes each encoding.

## Results

- All reconstructions were assessed using correlation ( $R^2$ ) with ground truth data Joint reconstruction and alternating trajectory performed best (Figs 3 and 4)
- The multidimensional point spread function (m-PSF) observations (Fig 5):
  - The m-PSF is **symmetrical** (Signal from component A aliases into component B in the same way that signal from B aliases into A, etc.)
  - Component mixing determined by energy of **off-diagonal blocks**
  - Alternating trajectory nulls high energy component (background)
  - Diagonal blocks unaffected** by which spokes are acquired in which encoding

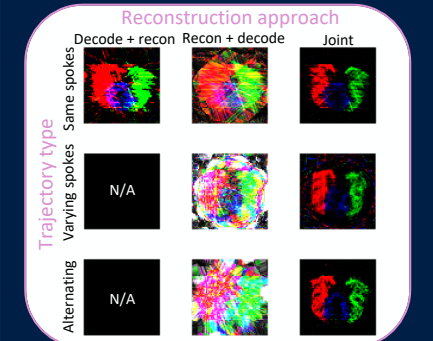


Fig 3 – Sharp and detailed reconstructions with only 16 spokes can be acquired with joint reconstruction and using the alternating spokes approach.

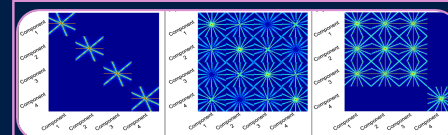


Fig 5 – Using same spokes each encoding results in no mixing of components (a). If each encoding uses a different trajectory all components mix (b). With the alternating approach one can stop one component from mixing (c). Through matching sampling and encoding we control aliasing in the component direction.

## Discussion

- Joint decoding and reconstruction gives **more degrees of freedom** and produces **better results**
  - Especially when optimised for energy distribution of data
- The **m-PSF can be used as a tool** to study interactions between trajectory and other types of signal encoding
- Simple case and theory presented here. **In-vivo trials presented in abstract #1073**
- Applications beyond ASL include e.g. 4D phase imaging<sup>4</sup>.



Watch a pre-recorded presentation [here](#)



Meet the author:  
Tue 11<sup>th</sup> August 2020, 10-12 AM (UTC), [here](#)

## REFERENCES:

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